

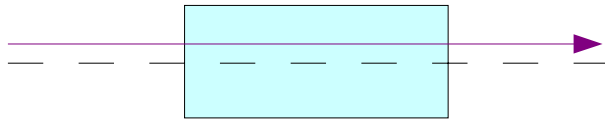
HOM Based Diagnostics at the TTF

Nov 14, 2005

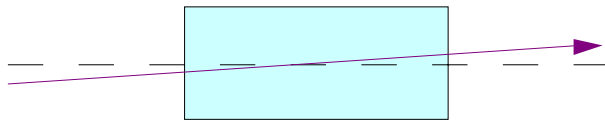
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With many contributions from the TTF team

Dipole Mode Response to Beam

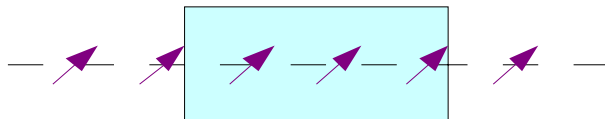


Beam position offset produces mode amplitude proportional to (position) X (charge)



Beam at angle produces signal at start of structure, cancels at end of structure:
Result is “derivative” like signal, 90 degrees out of phase with position signal

Amplitude is proportional to (Angle) X (charge) X (cavity length)



Bunch tilt signal produces a signal with the same phase as the beam angle signal

Amplitude is proportional to (Tilt) X (charge) X (bunch length)

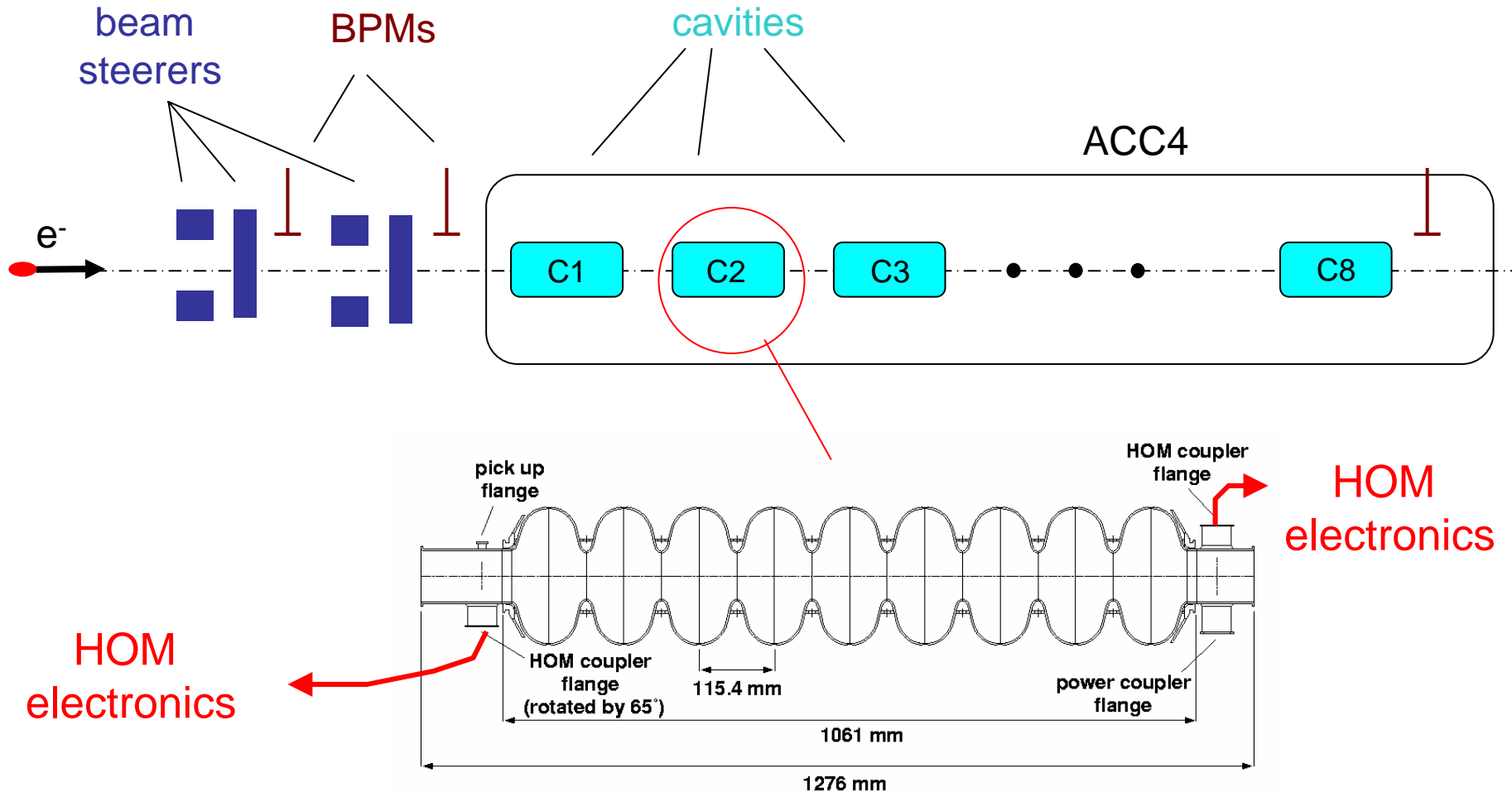
Not significant for the DESY TTF (bunches are very short)

Note that centers (position / angle for zero signal) of HOM modes are modified by asymmetric couplers at the ~100 micron level

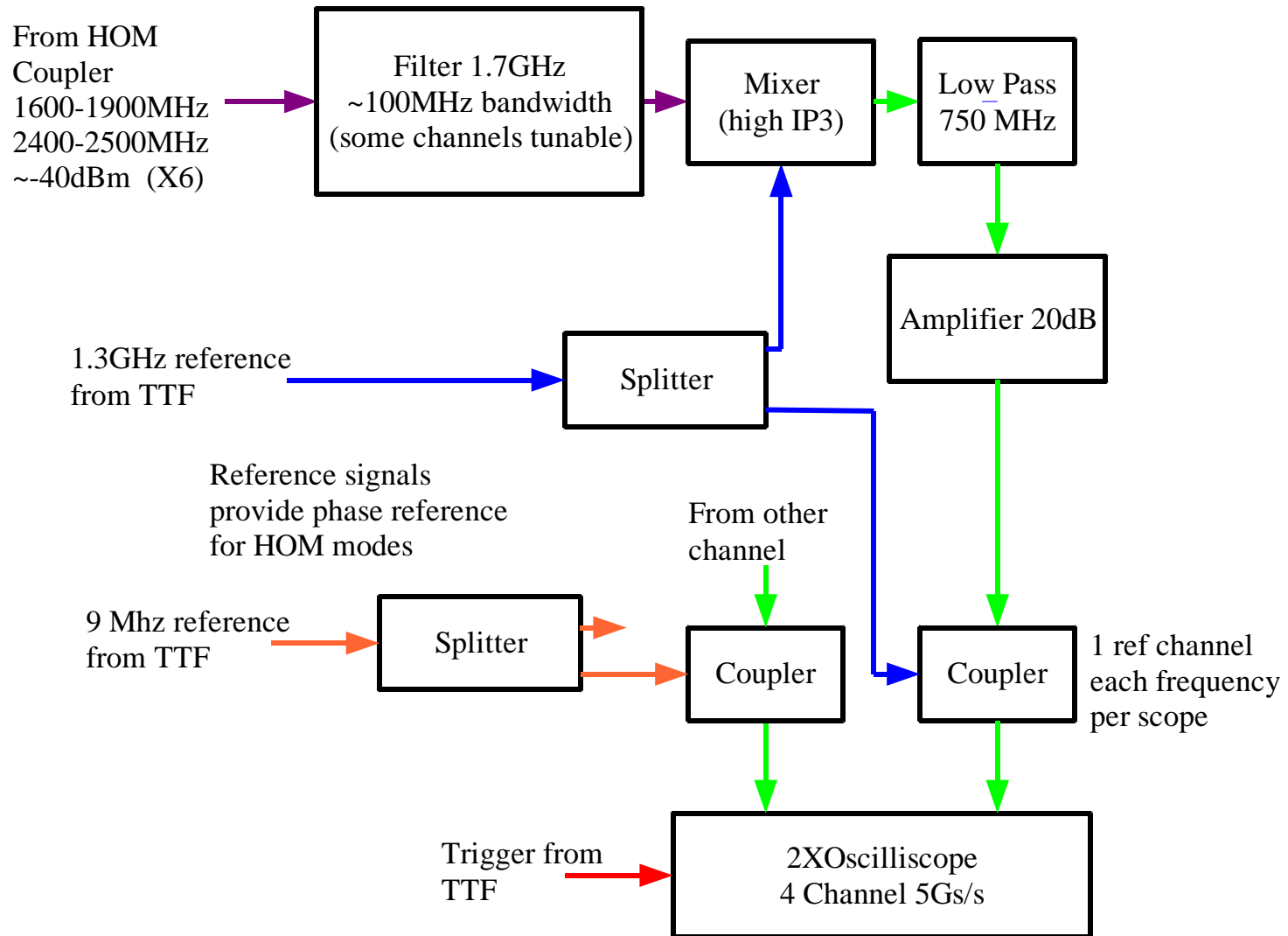
HOM Modes For This Study

- In addition to the 1.3 GHz accelerating mode, the SC cavities support higher order modes with frequencies above approximately 1.6 GHz.
- We primarily use the Dipole TE₁₁₁-6 (~1700MHz), TE₁₁₁-7 (~1730MHz) Modes, and the TM₁₁₀-4 (~1860MHz) mode. These are the near-speed-of-light dipole modes which couple most strongly to the beam.
- Experiments were done primarily in ACC4, with some tests in ACC1.

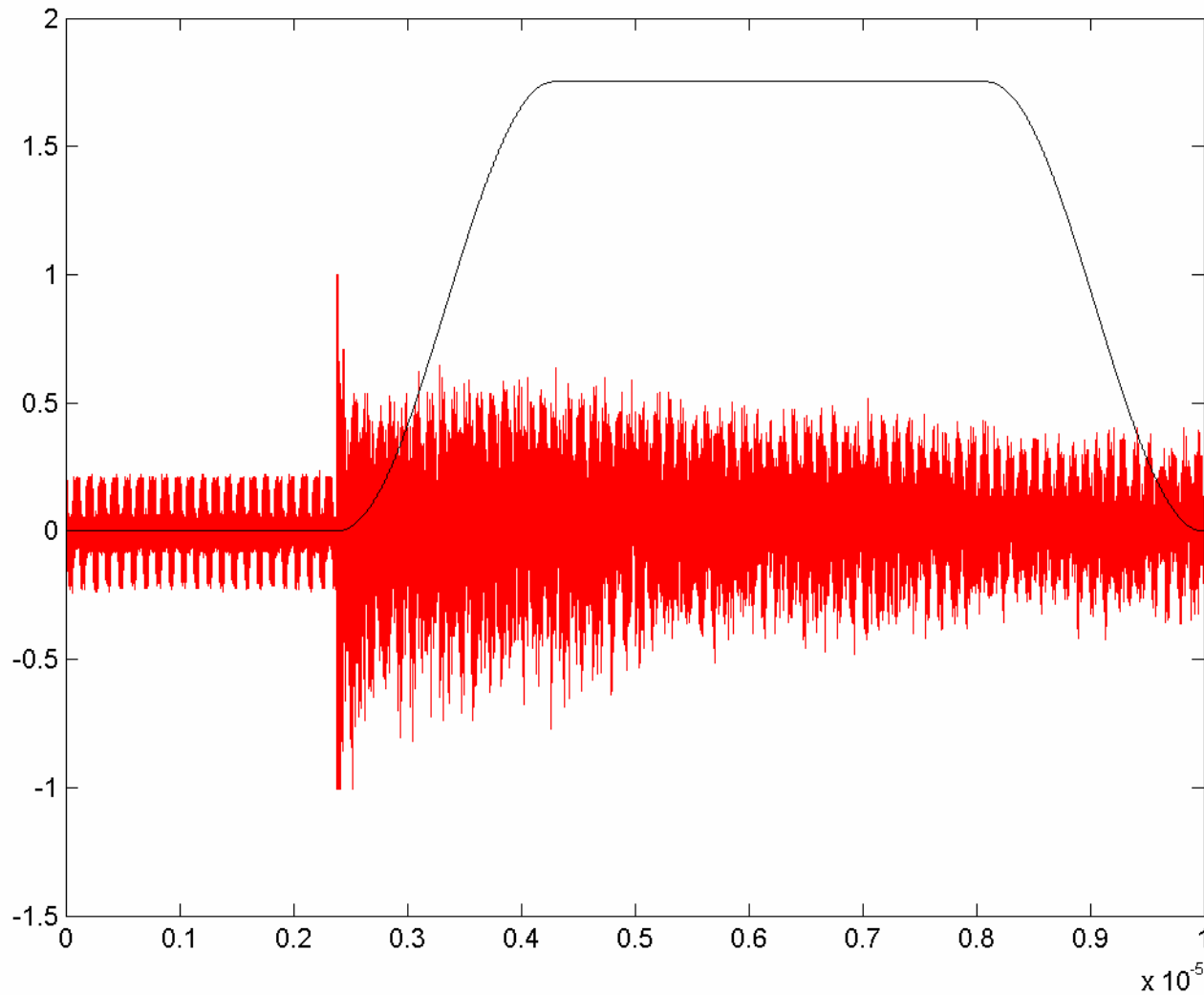
Experimental Setup - ACC4



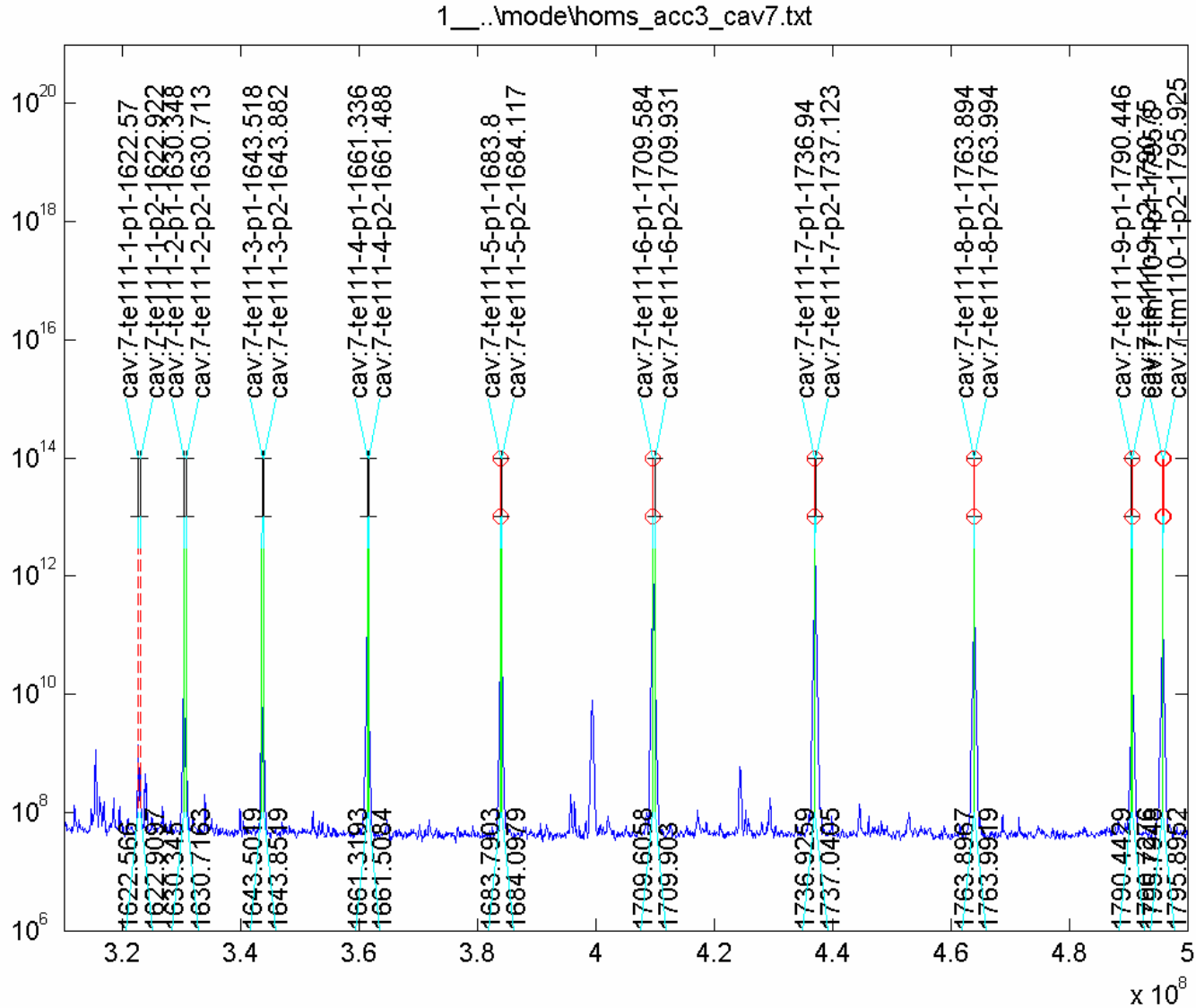
HOM Measurement Electronics



Raw Scope Waveform



HOM Spectrum near TE111 modes



Signal Analysis for Beam Position

- Use conventional BPMs before and after structure to define beam position and angle at the cavities.
- For HOM signals, measure complex amplitude at line frequencies
 - Each “line”, e.g. TE₁₁₁-6 has 2 polarizations, at slightly different frequencies
 - Each cavity has 2 HOM ports
 - Complex signal has 2 real degrees of freedom
 - Get 8 real measurements / cavity (for 1 mode).

Linear Regression

- Given a set of measurements for a set of variables, predict the measurements for one variable based on the others.
- Prediction is a linear combination of the other variables for that measurement.
- Linear combination is chosen to minimize the RMS error of the prediction of the variable over all measurements.
- **Need more measurements than variables!!!**
- Can also use to predict X and Y, from mode components.

Set of Measurements $M_{a,b}$ on the “reference” mode where “a” is the data set (1:100 for our data), and “b” is one of the 8 components of the mode:

Polarization 1 or 2

Coupler 1 or 2

Real or Imaginary part

$$\begin{bmatrix} M_{1,1} & \dots & M_{1,8} & 1 \\ M_{2,1} & \dots & \dots & 1 \\ \dots & \dots & \dots & 1 \\ M_{100,1} & \dots & M_{100,8} & 1 \end{bmatrix} \begin{bmatrix} R_1 \\ \dots \\ R_9 \end{bmatrix} = \begin{bmatrix} M_{1,x} \\ M_{2,x} \\ \dots \\ M_{100,x} \end{bmatrix}$$

Set of measurements from the BPMs X is a single component (out of X,X',Y,Y') for the target mode.

Set of coefficients which best (in a “least squares” sense) predict the BPM measurement

“Ones” allow for offsets
In modes vs. BPMs

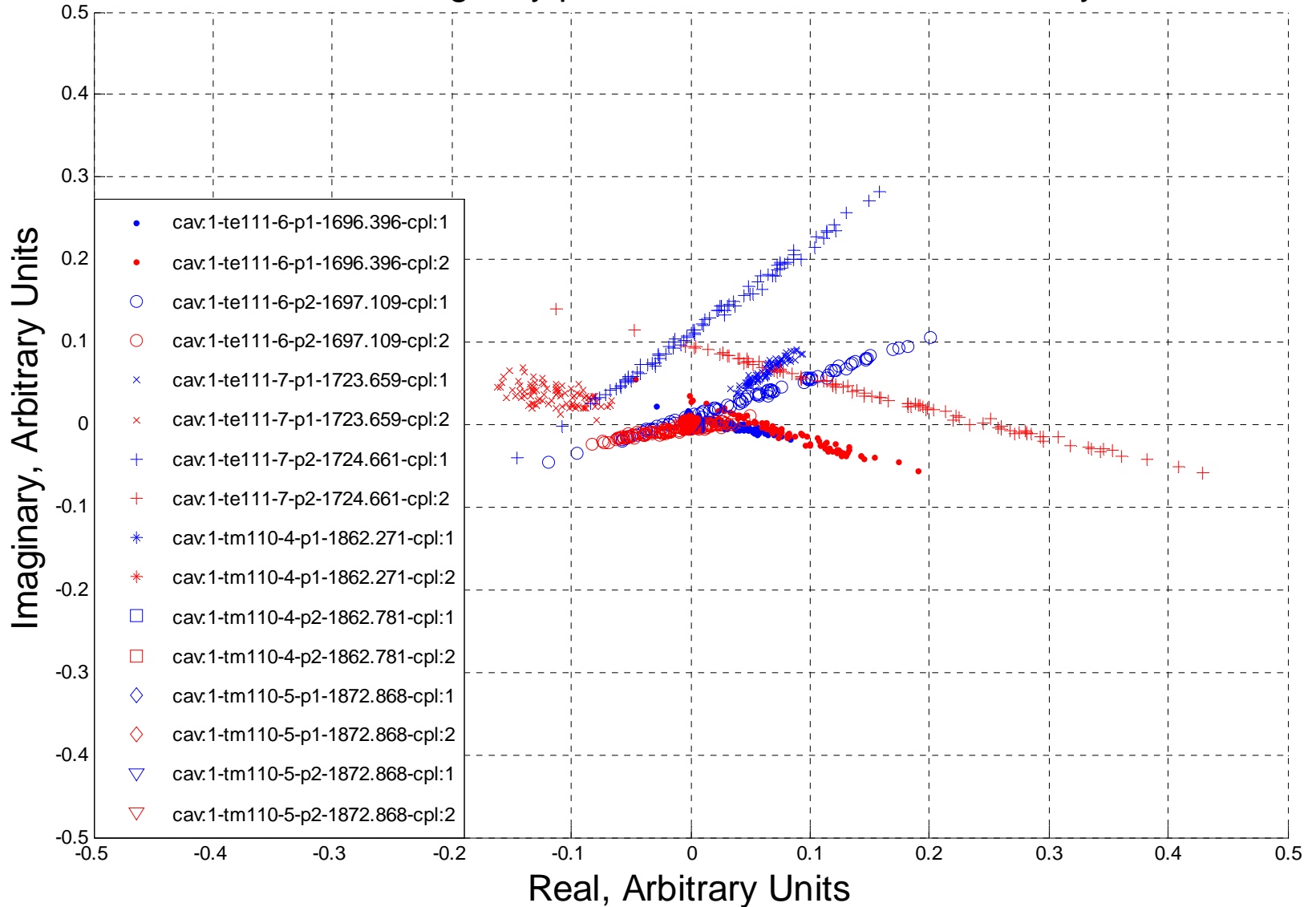
These coefficients R are found by “linear regression”, in our case the arithmetic is done by *Matlab*.

Experimental setup for HOM Mode Regression against BPMs

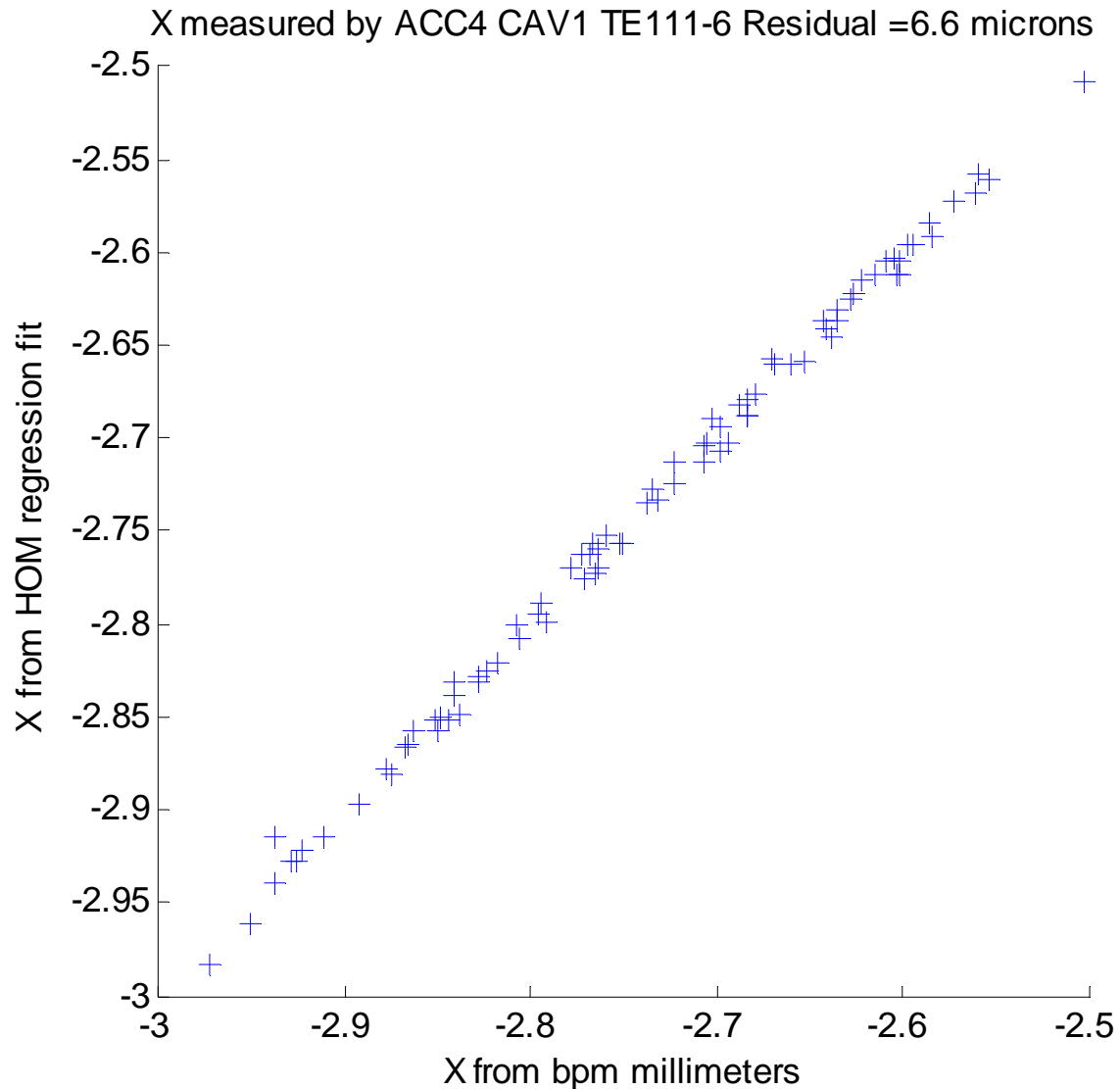
- Use ACC4. All cavities measured, several modes. CAV1 measurements, TE111-6 shown.
 - Really “typical”: haven’t had time to find plots with best resolution
- Use BPMs just upstream and downstream of ACC4
- HOM signals measured without pre-amplifiers to provide larger range (for cavity alignment studies).
 - Approximately 10dB increase in noise figure.
- Resolution measurements include conventional BPM resolution

Hom Mode vectors during corrector scan (4-d scan)

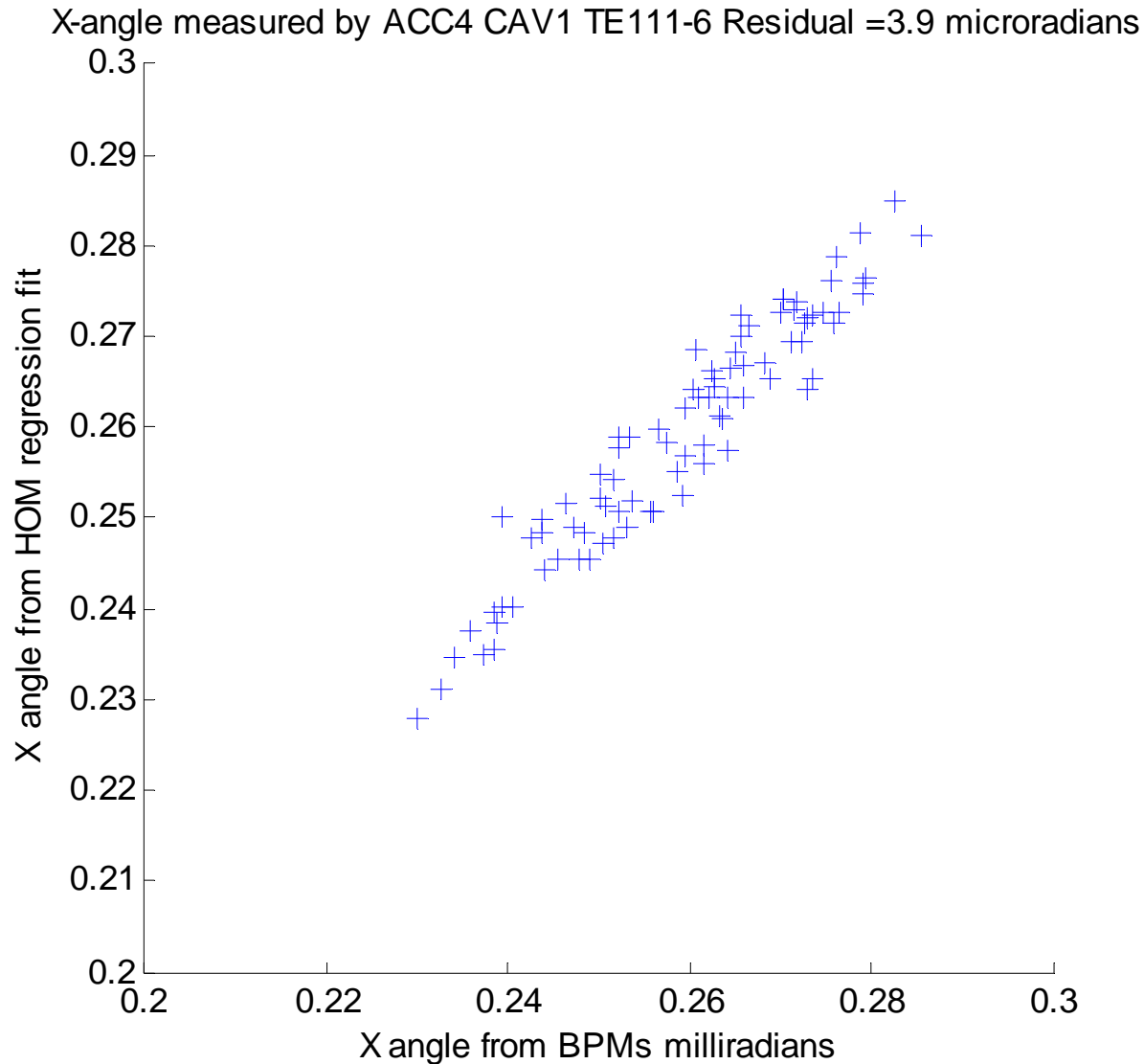
Real vs. Imaginary part of HOM modes, ACC4 Cavity 1



HOM Mode regression for X

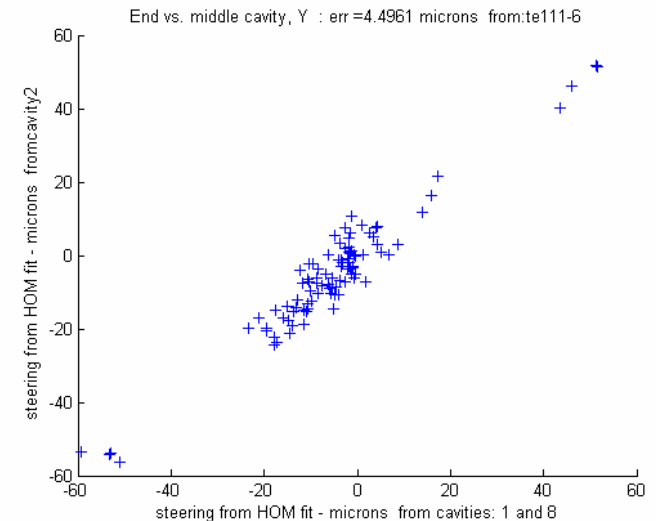


HOM mode regression for X angle.



HOM BPM resolution

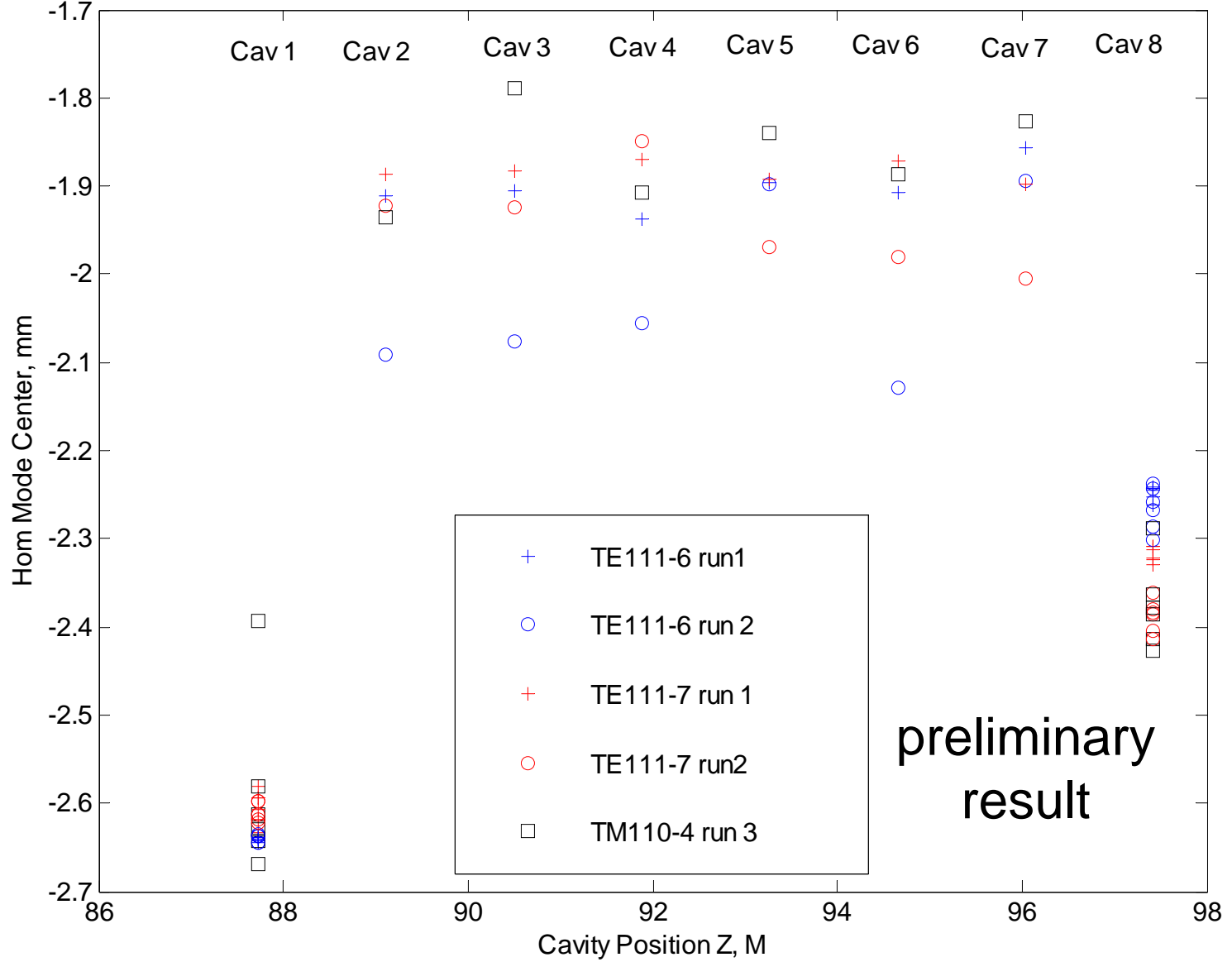
- 7 micron, 4 micron-radian resolution.
 - Consistent with ~1 meter lever arm for angular resolution
 - Indicates that conventional BPM resolution better than ~10 microns. (not limited)
- Dynamic range ~ 1 millimeter (with this gain / attenuation)
- Previous test of HOM mode resolution (end cavities vs. center cavity) gave 3 micron resolution
 - Test done with preamplifiers – but in an earlier hardware configuration



Cavity Alignment from HOM modes

- Several analysis methods tried – so far best appears to be:
 - Record HOM signals and conventional BPMs for a series of machine cycles
 - Find HOM (complex) amplitudes as a function of frequency (from FFT)
 - Linear Regression / Singular Value Decomposition to find matrix between HOM amplitudes and BPMs
 - Find beam position / angle corresponding to zero HOM signals in each cavity.
- Work still preliminary

Cavity X Alignment ACC4



Cavity Center Measurement Issues

- HOMs have few micron resolution
 - Would expect cavity resolution to similar level
 - See resolution worse than 100 microns

WHY?

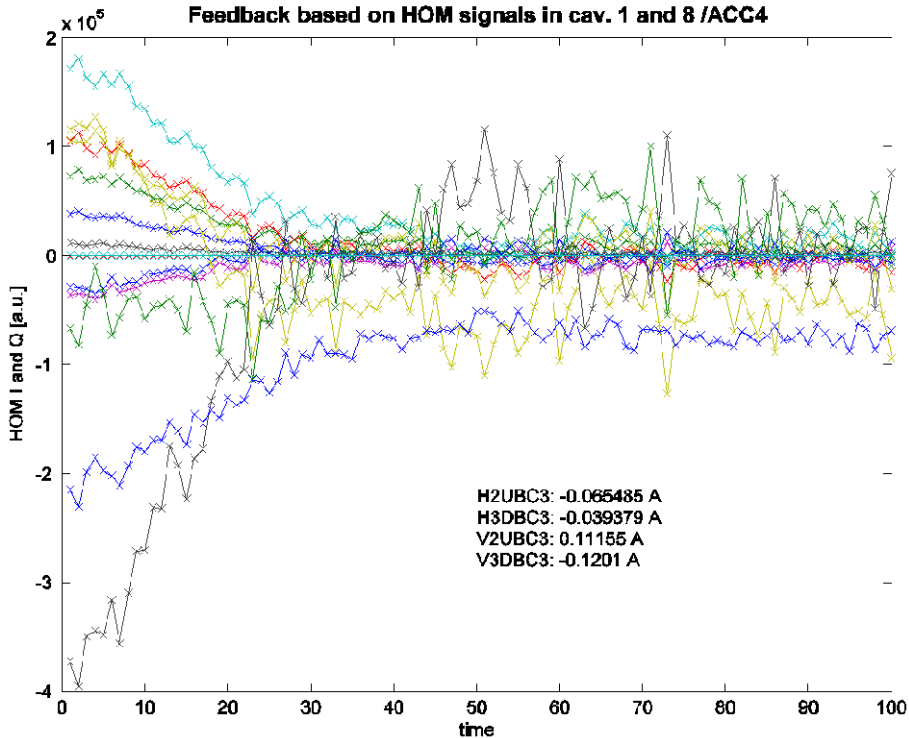
- Beam trajectories not steered through zero in angle.
 - Must project angles to zero – introduces errors
 - Can't "ignore" angle – it is related to position by RF phase angle.
 - In future (this week?) use feedback to stabilize on position and angle for each cavity in sequence
- 8 HOM degrees of freedom (2X coupler, 2X mode polarization, 2X real / imaginary), represent 4 real degrees of freedom (X, X', Y, Y')
 - Need to understand how to treat correctly
 - Some cavities, polarization frequencies are degenerate
 - Need both couplers, but only 1 line
 - Some cavities polarization frequencies are well separated
 - Need both lines, but only 1 coupler.
 - Many cavities are partially degenerate
 - Need help with the math.

HOM Based Beam Feedback

- Do a calibration of HOM mode (complex) amplitudes against two sets of X,Y correctors.
 - Linear regression, similar to what we did for BPMs described earlier
 - Use first and last cavity in a structure
- Feedback adjusts the correctors to minimize HOM amplitudes.
 - 2 cavities, have 16 real measurements
 - 4 control degrees of freedom
 - Combine feedback signals for all modes -> minimizes RMS
- Two experiments:
 - ACC4, cavities 1 and 8
 - ACC1, cavities 1 and 8
- In each case plot the 16 real amplitudes (2 cavities X 2 couplers X 2 frequencies X real / imaginary part) for each machine cycle.

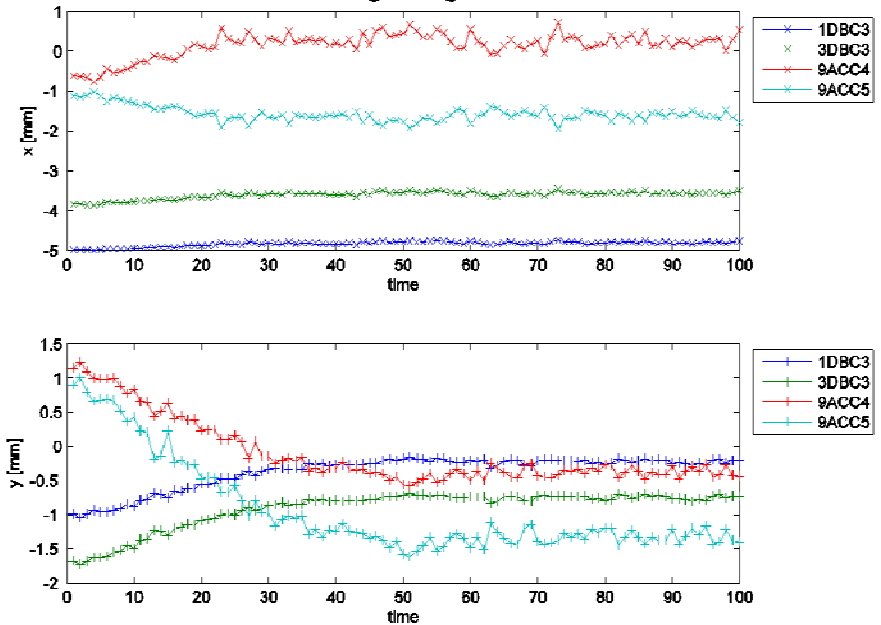
ACC 4 Feedback

Feedback based on HOM signals in cav. 1 and 8 /ACC4



HOM mode component amplitudes during feedback, vs. machine cycle

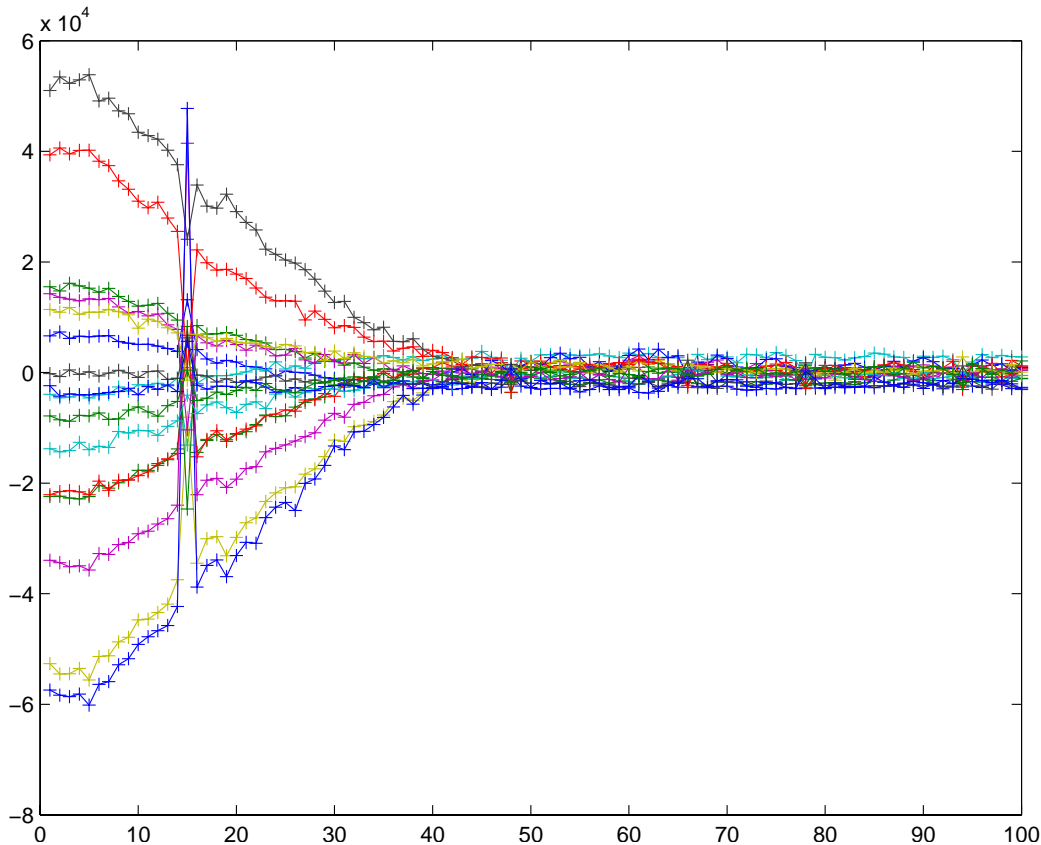
BPM readings during feedback



Conventional BPMs during feedback

Beam position and angle set to minimize total power in TE111-6 modes in Cavities 1 and 8 of ACC4

ACC1 Feedback



HOM mode component amplitudes during feedback, vs. machine cycle

Feedback minimized HOM Power.

Emittance optimized before feedback operation 1.6X1.8 (90%)

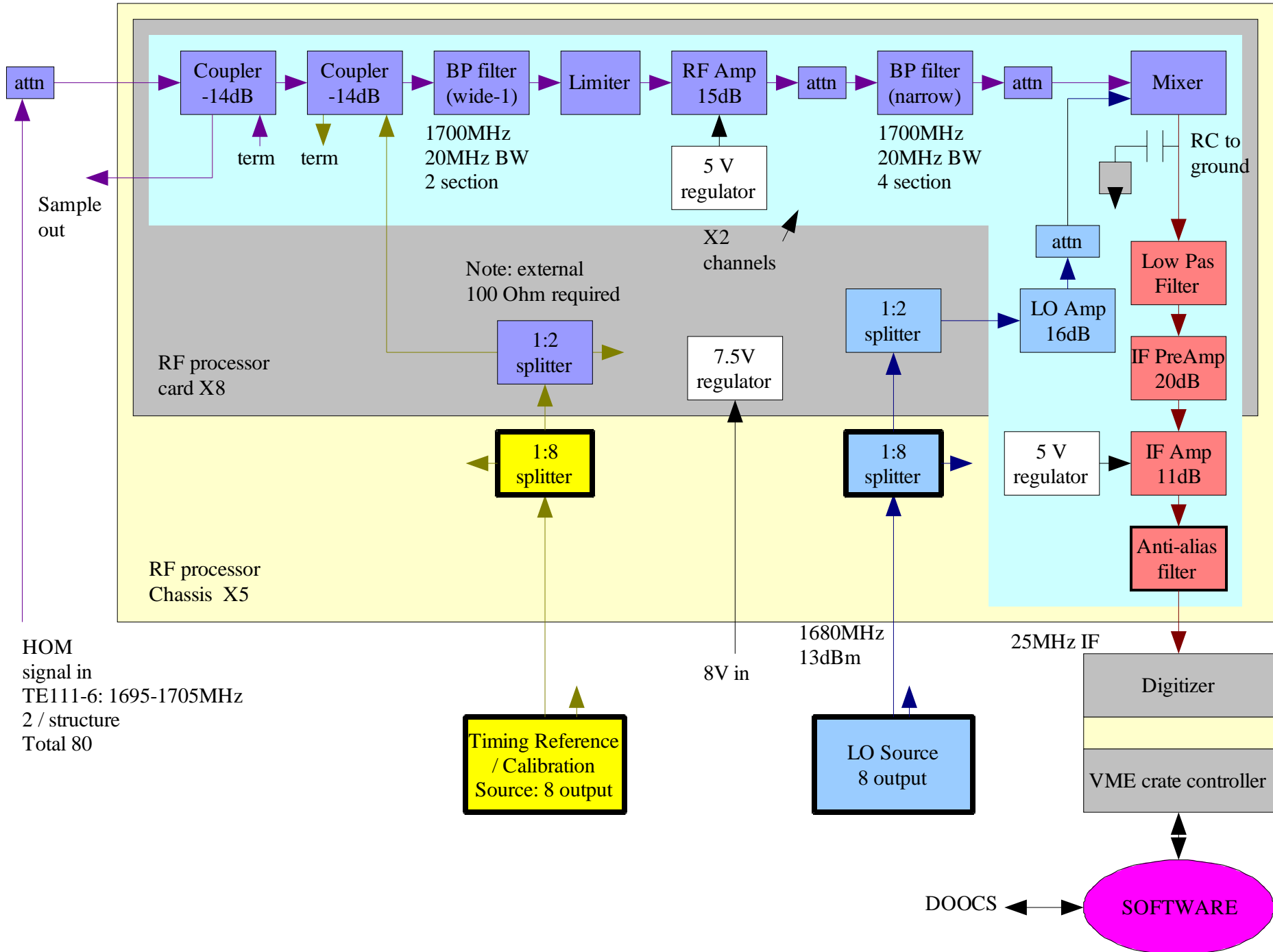
After feedback, Emittance slightly improved 1.6X1.6 (90%) (not clear if this is statistically significant)

Beam not tuned after feedback

Note, jump due to phase error (2π wrap problem)

HOM Diagnostic System for Full TTF Linac

- Want to simultaneously instrument all 40 cavities in the TTF
 - Need 80 channels of data acquisition
- Scope based system (used for previous measurements) requires one (4 channel, 5Gs/s) scope for 2 cavities.
 - 20 scopes, at ~30,000 € is too expensive
- Build narrow band (10MHz BW) system
 - Downmix to 25MHz IF
 - Digitizer with 100Ms/s, 14 bit digitizers (SIS3301 8 channel VME modules)
 - System hardware cost ~ 100,000 € for full system.
- Narrow band system can only measure 1 mode – choose TE111-6
 - 10 MHz bandwidth input filters
- Theoretical noise similar to existing HOM system
- Linearity / dynamic range expected ~20dB better than existing system.
- Expect 1 micron resolution at 1 millimeter dynamic range.



HOM Downmix Board

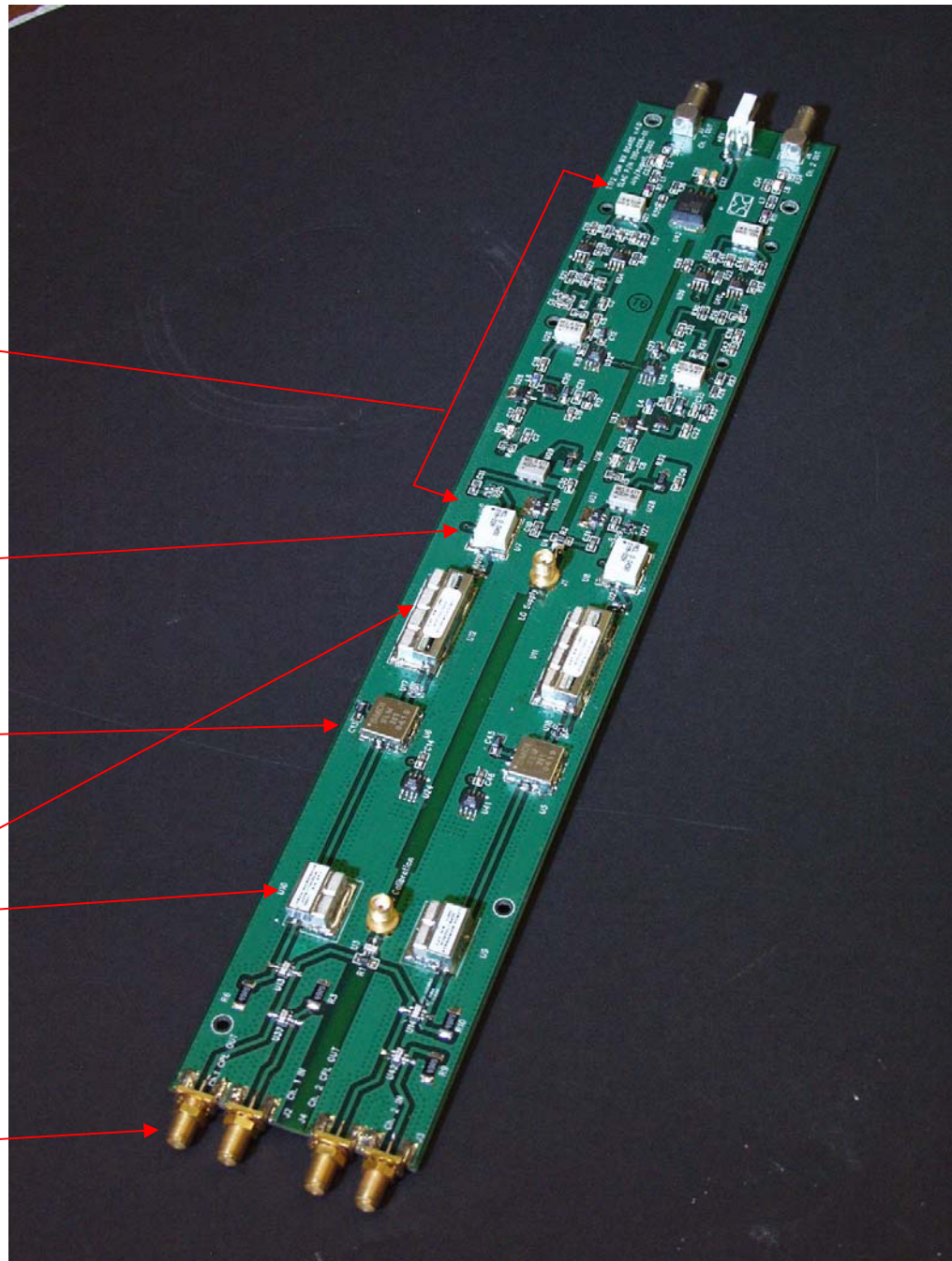
IF output amplifier

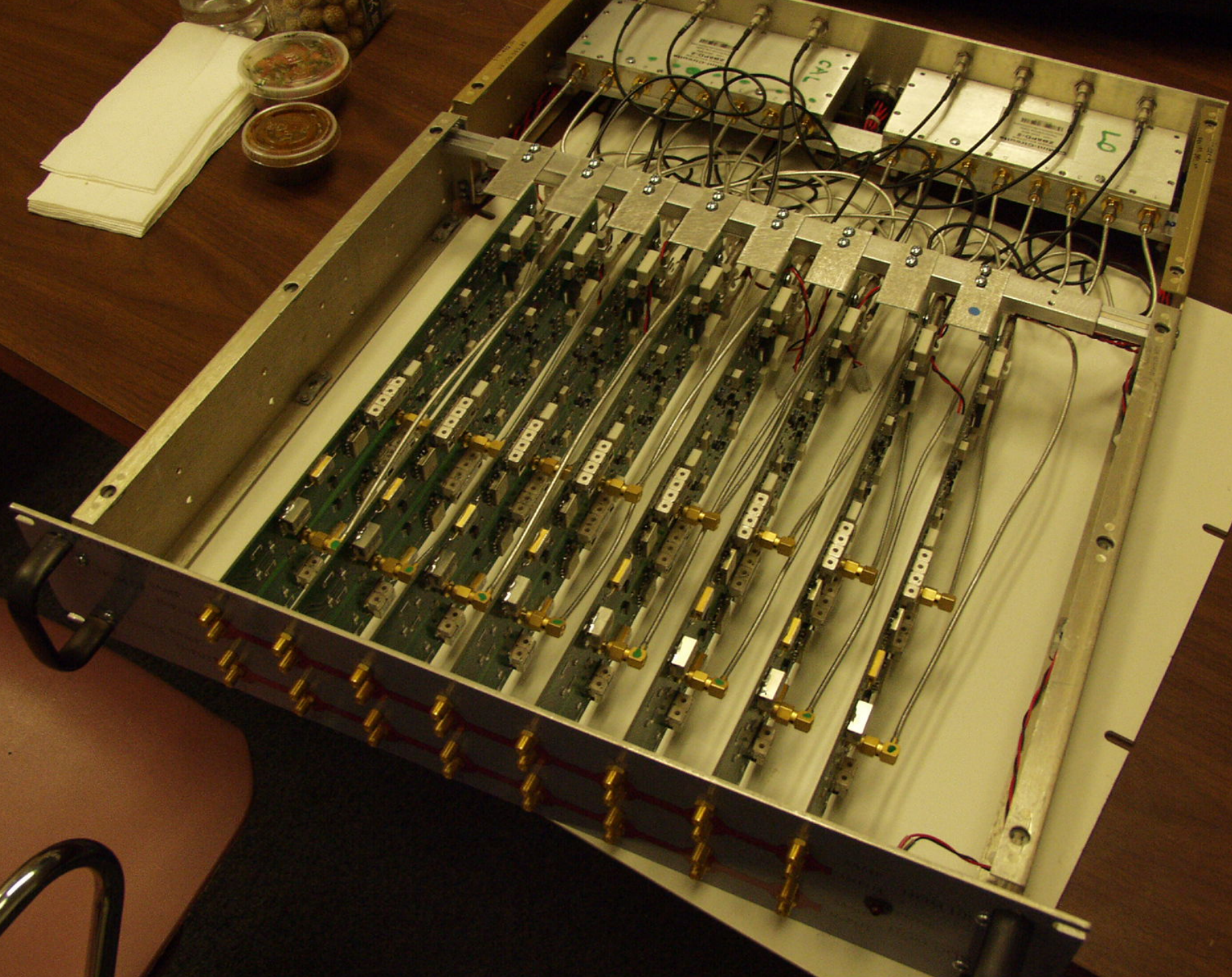
Mixer

Pre-amplifier

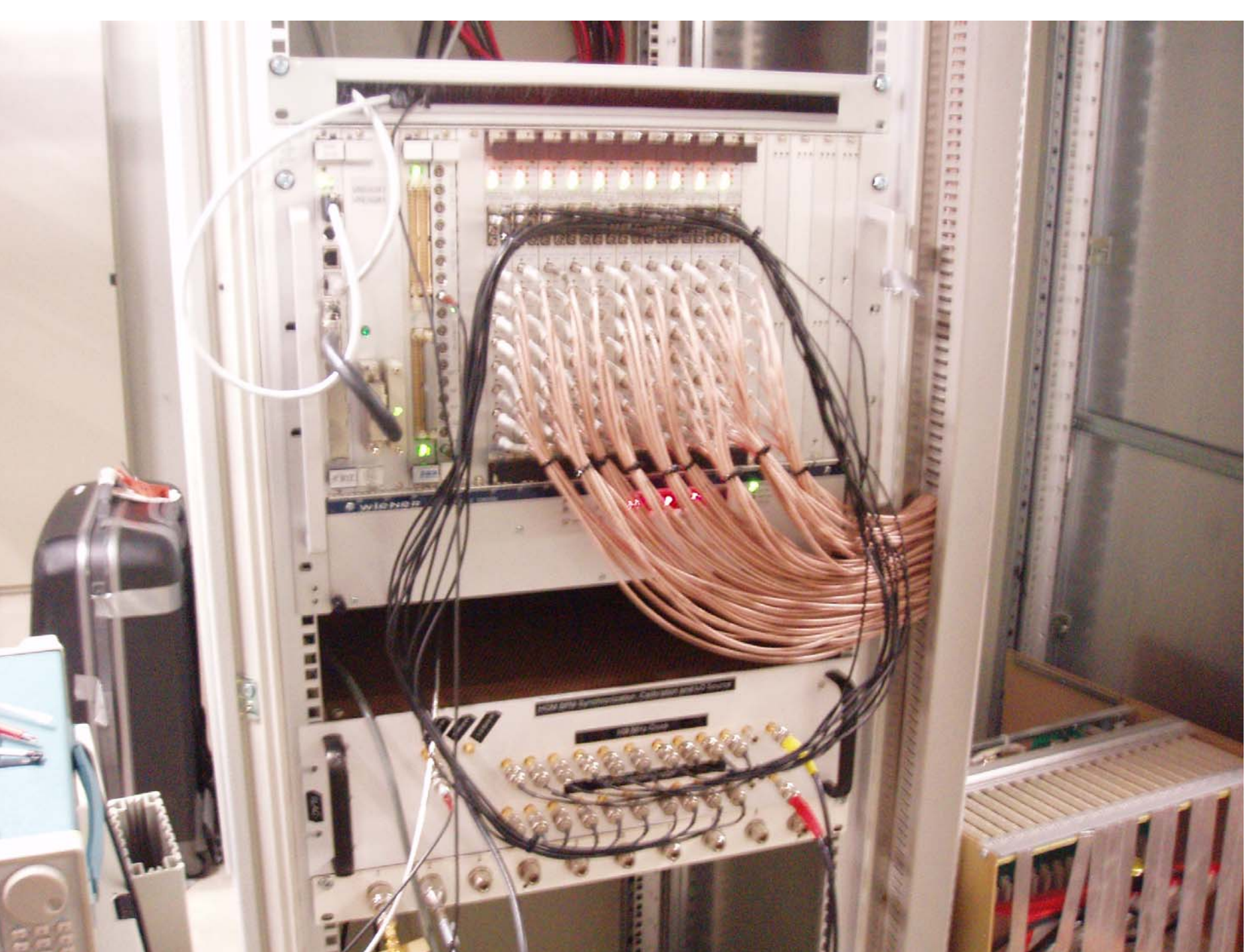
Bandpass filters

Input and sample out

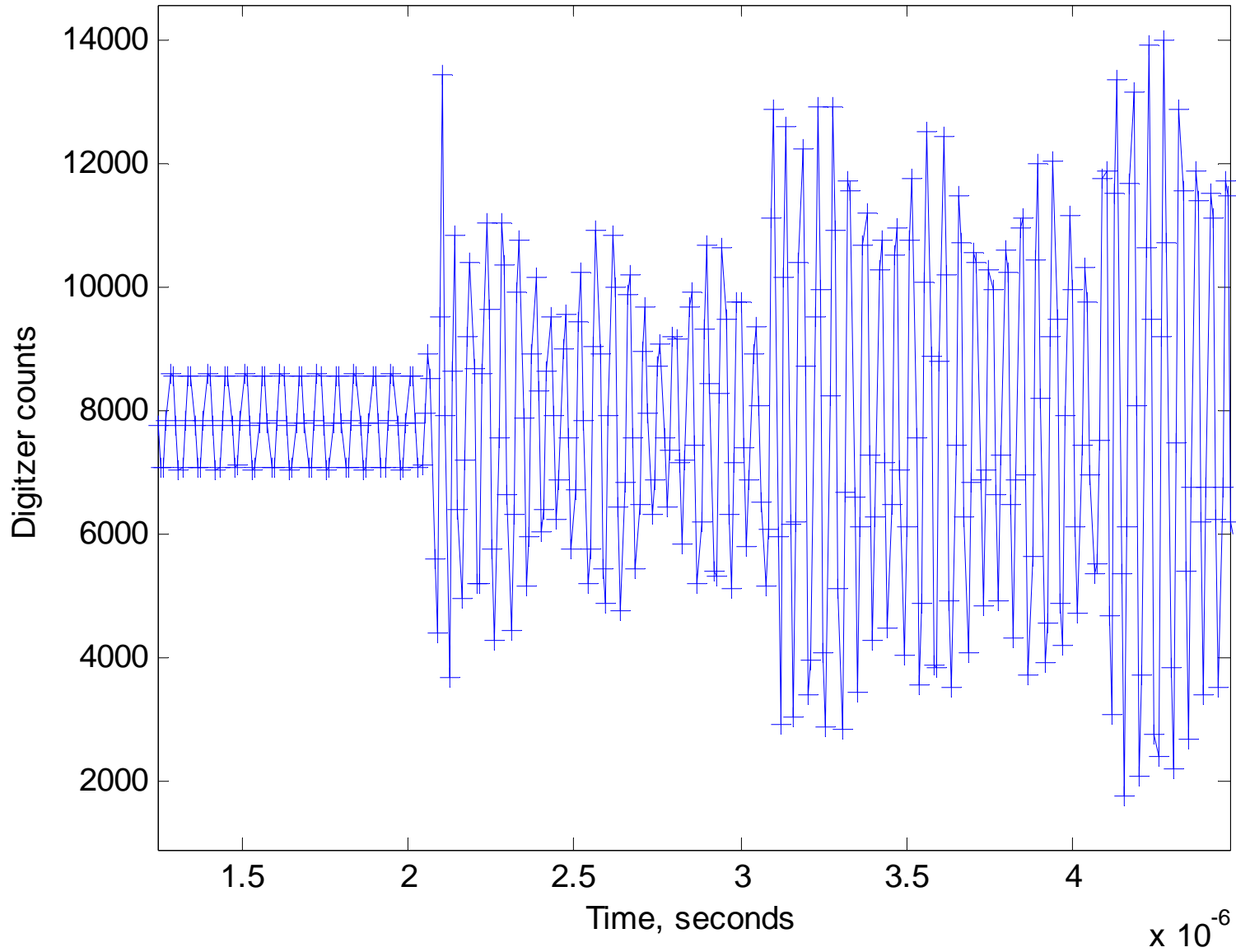








New DAQ system plot (multi-bunch)



Multi-bunch operation

- New hardware can digitizer signals for the full length of the TTF bunch train. >1 millisecond.
- At each bunch passage, field amplitude from the bunch adds to the existing field amplitude.
- Fields from previous bunches decay at a predictable rate
- Only care about field after passage of previous bunch – History does not matter.
- Can subtract (decayed) fields at time of previous bunch to find new contribution.
- Effective integration time ~ 1 microsecond (rather than ~ 10 currently used). Will reduce resolution, but still expect <10 microns.

HOM System Applications

- Real time BPM – all cavities in TTF
 - Expect single bunch resolution ~1 micron
 - 3 micron demonstrated
 - Measure each bunch in train to ~10 microns
 - Multi-bunch measurement not yet demonstrated
 - **Need automated calibration and integration with DOOCS.**
- HOM mode minimization feedback
 - Should improve emittance
 - Demonstrated for 2 cavities in one structure
 - Should be possible to feedback to beam orbit which minimizes HOM power in full machine.
 - **Need to integrate with DESY feedback system**
- Measure / monitor cavity alignment within structures
 - Preliminary results suggest ~100 micron resolution
 - Expect few micron results
 - Work ongoing.